

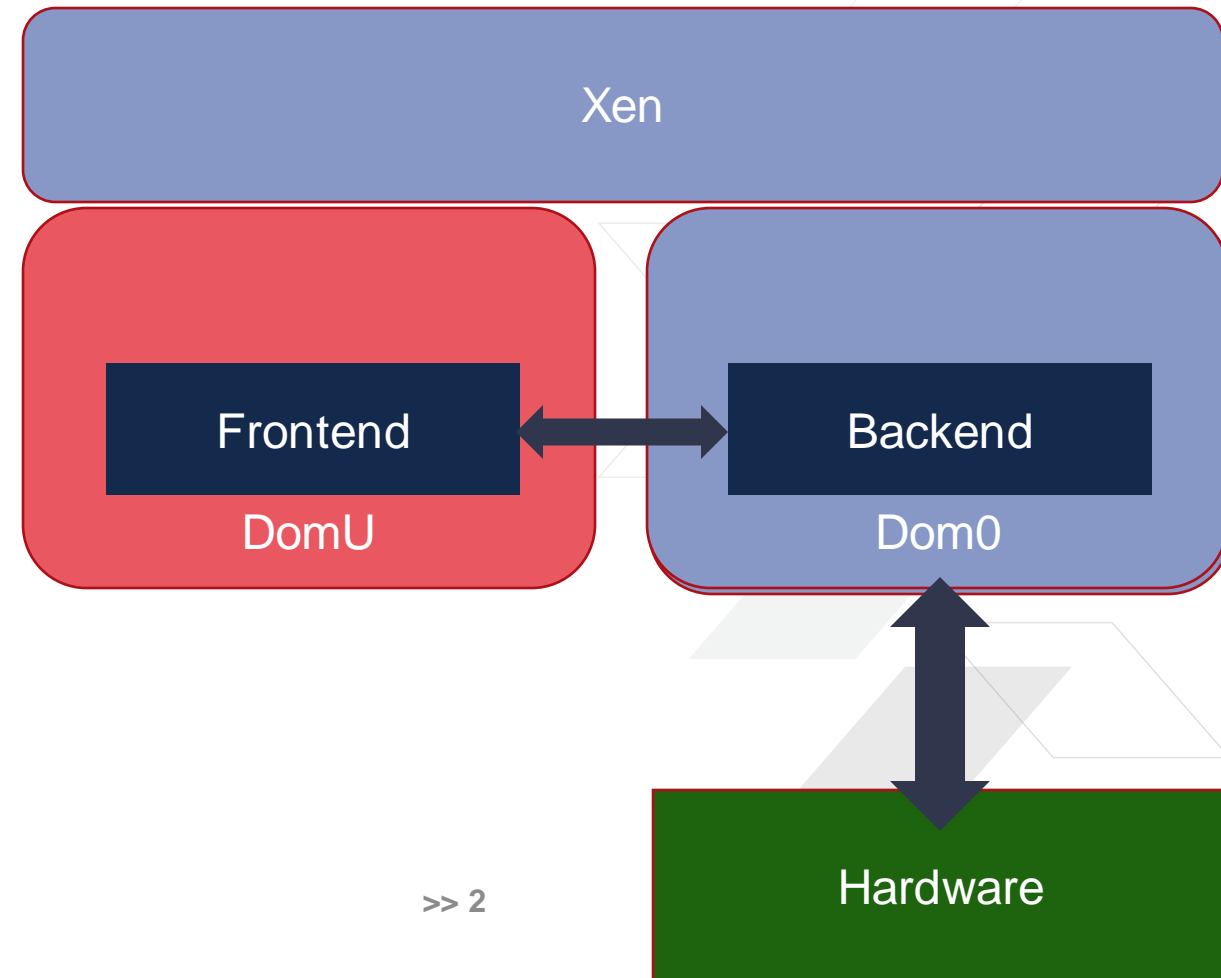
# VM-to-VM Communication Mechanisms for Embedded

Stefano Stabellini



# Existing VM-to-VM Communication Mechanisms

- > **Existing protocols: Xen PV Drivers, VirtIO**
  - >> discoverable and dynamic
  - >> create new connections at runtime
  - >> made for IO virtualization
- > **A frontend in the guest connects to the backend in Dom0 / hypervisor**
- > **Created to virtualize devices**
- > **Typically based on memory sharing**
- > **VirtIO expects privileged backends**

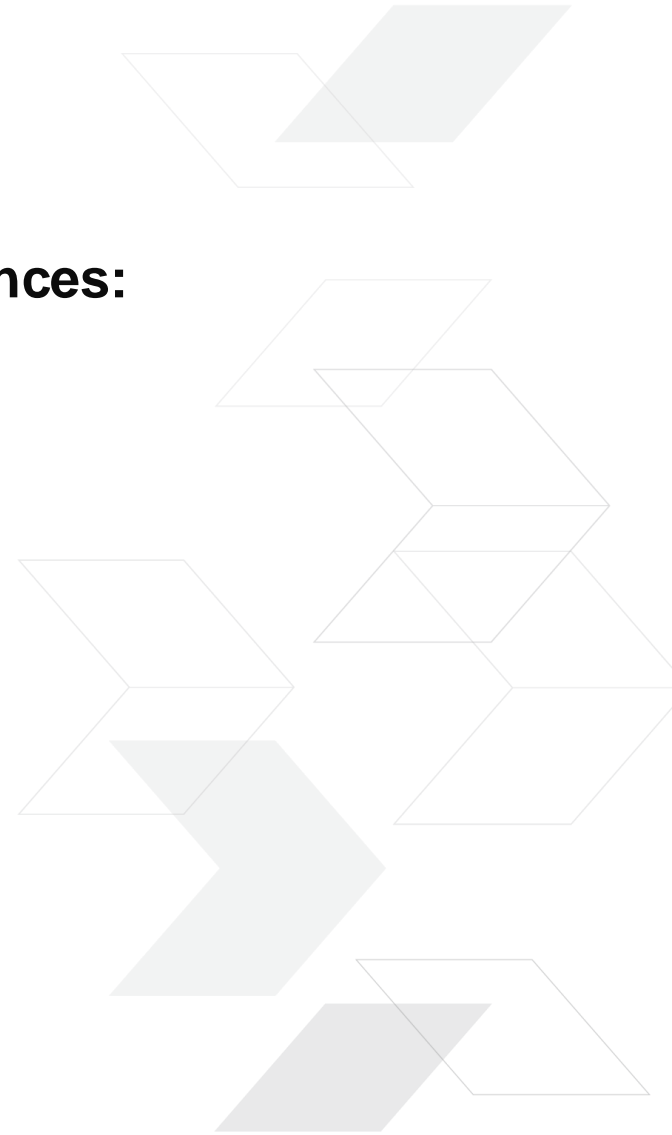


# Static Partitioning

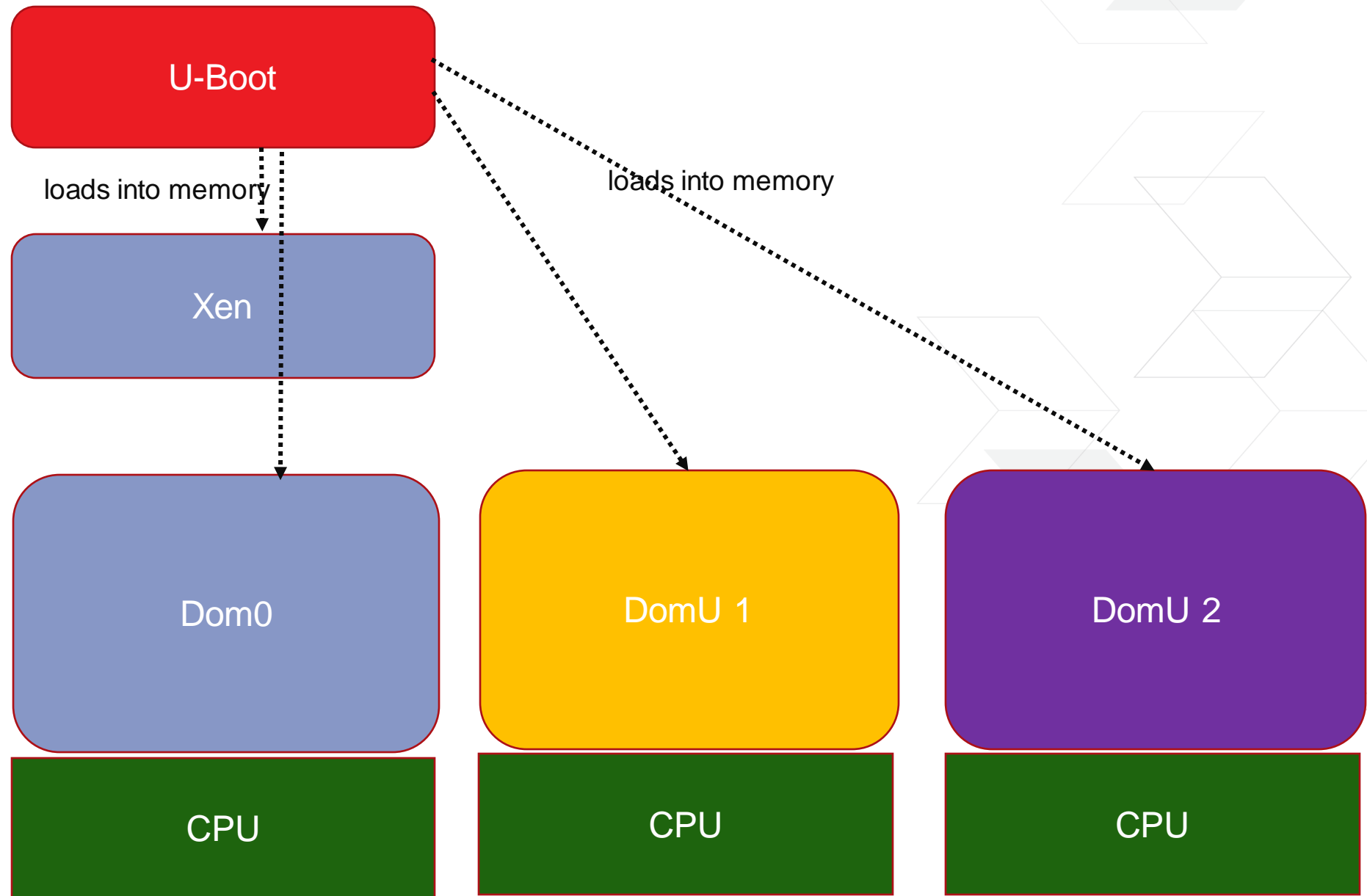


# Static Partitioning

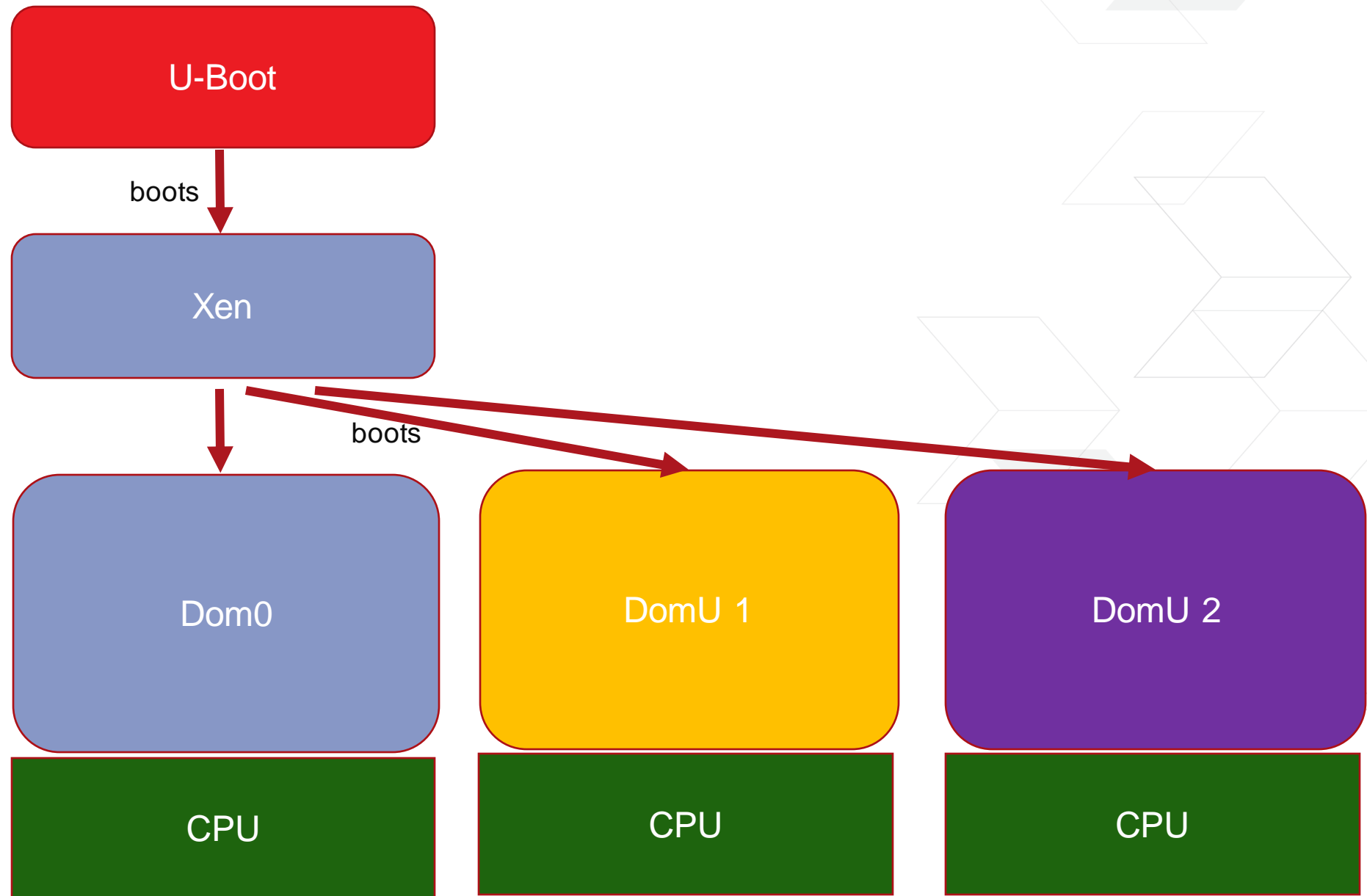
- > **Static Partitioning is similar to virtualization with some key differences:**
  - >> No dynamic VMs, a limited number of "partitions" instead
  - >> Focus on direct assignment of hardware resources
  - >> Configuration defined at "Build Time"
  - >> Real-Time, Safety, and Short Boot Times are often key requirements
- > **Example: Xen Dom0less**



# Xen Dom0less



# Xen Dom0less



# Xen Dom0less Current Status

- > **Static Partitions defined at build time**
- > **Fast boot times, real-time support, easier to safety-certify**
- > **Dom0 is not required**
- > **No "out of the box" communication mechanisms available**



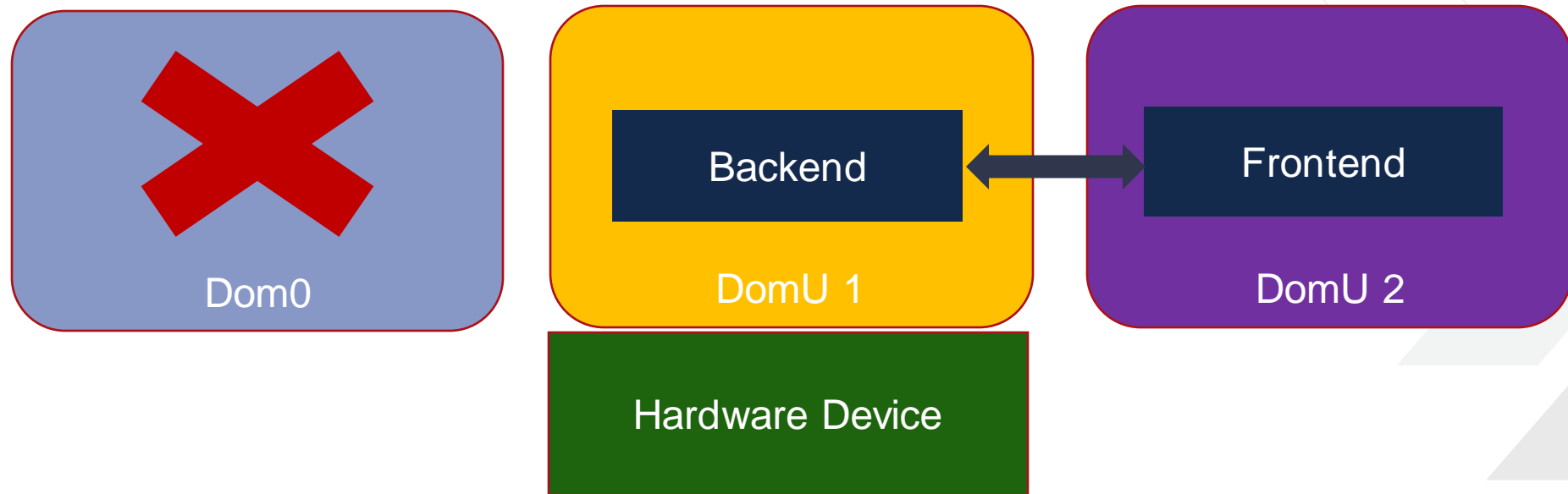
# Static Partitioning and Communication

- > **Often only VM-to-VM communication is required, not device virtualization**
  - >> There are enough physical devices to directly assign them to VMs as needed
  - >> Device virtualization can be interesting for sharing an SD card among multiple VMs
- > **VM-to-VM communication is different from device virtualization**
  - >> A simple VM-to-VM channel to send and receive raw data
  - >> It doesn't need "frontends" and "backends"
  - >> It requires a smaller code base
  - >> It is faster for exchanging data but it is unwieldy for virtualizing devices
- > **Static definition of VM-to-VM communication channels**
  - >> Define connections at "build time"
  - >> Required for safety
- > **No privileged backends**
  - >> Required for safety
- > **Support Linux and non-Linux guests (Zephyr, FreeRTOS, WindRiver, QNX, etc.)**



# Static Partitioning VM-to-VM communication

> No privileged backends

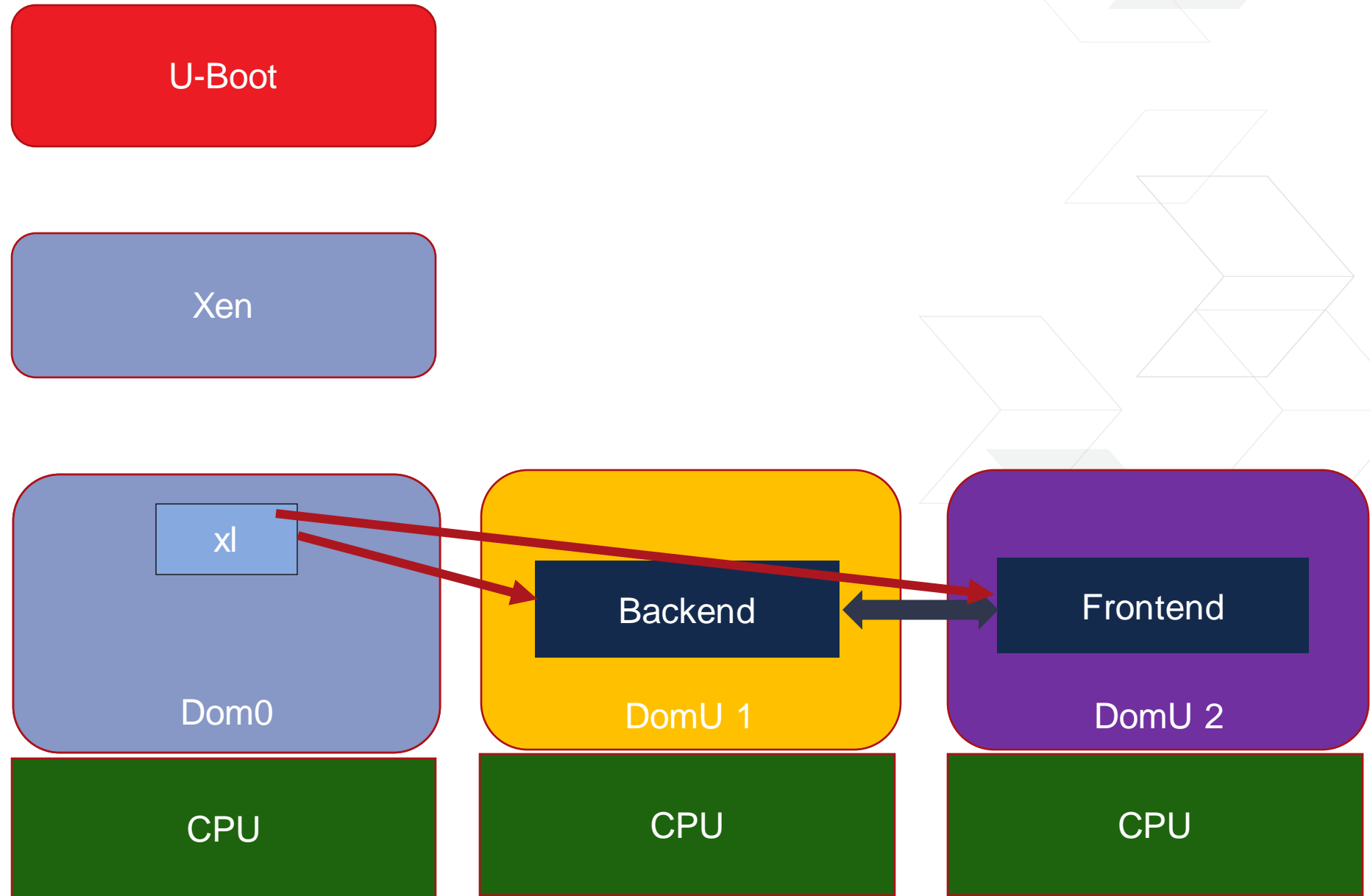


# Xen PV Drivers

- > **Solid and hardened in production for years (AWS)**
- > **Made for device virtualization, can be used for communication:**
  - >> Network
  - >> Block (disks)
  - >> Console
  - >> 2D graphics, mouse and keyboard
  - >> Sound
  - >> Etc.
- > **Pros:**
  - >> Very Fast Unprivileged Backends
  - >> Available for Linux, BSDs and Windows, less common among RTOSes
- > **Cons:**
  - >> Might not be available in certain embedded RTOSes (but BSD versions exist for all PV drivers)
  - >> Dom0less support is work-in-progress



# Xen PV Drivers and Dom0less

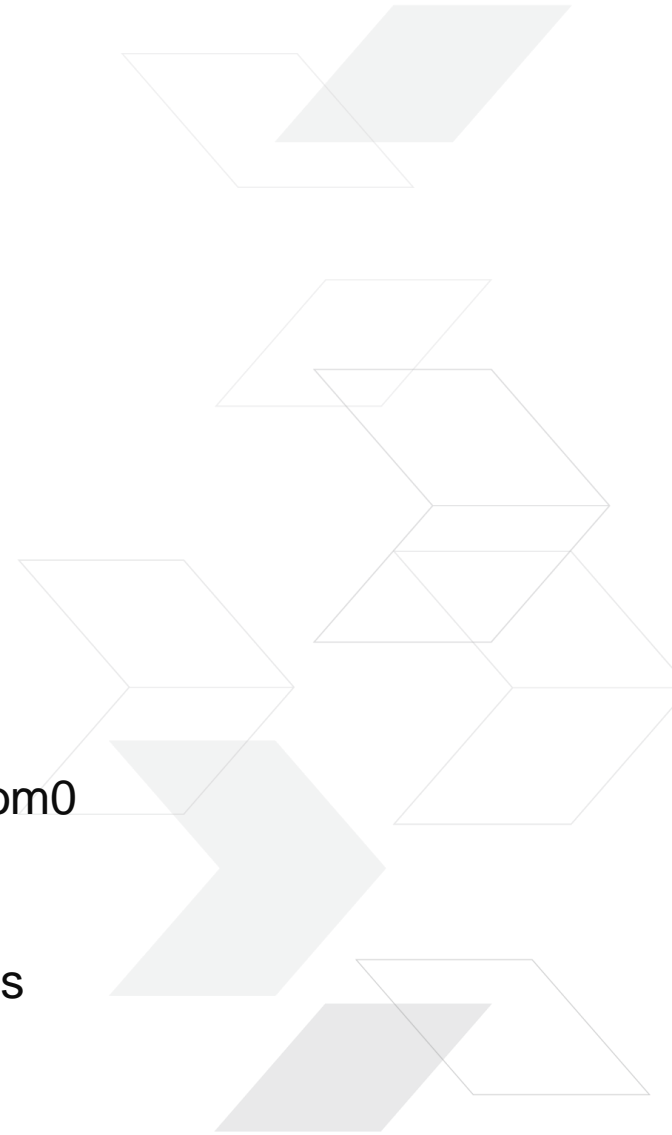


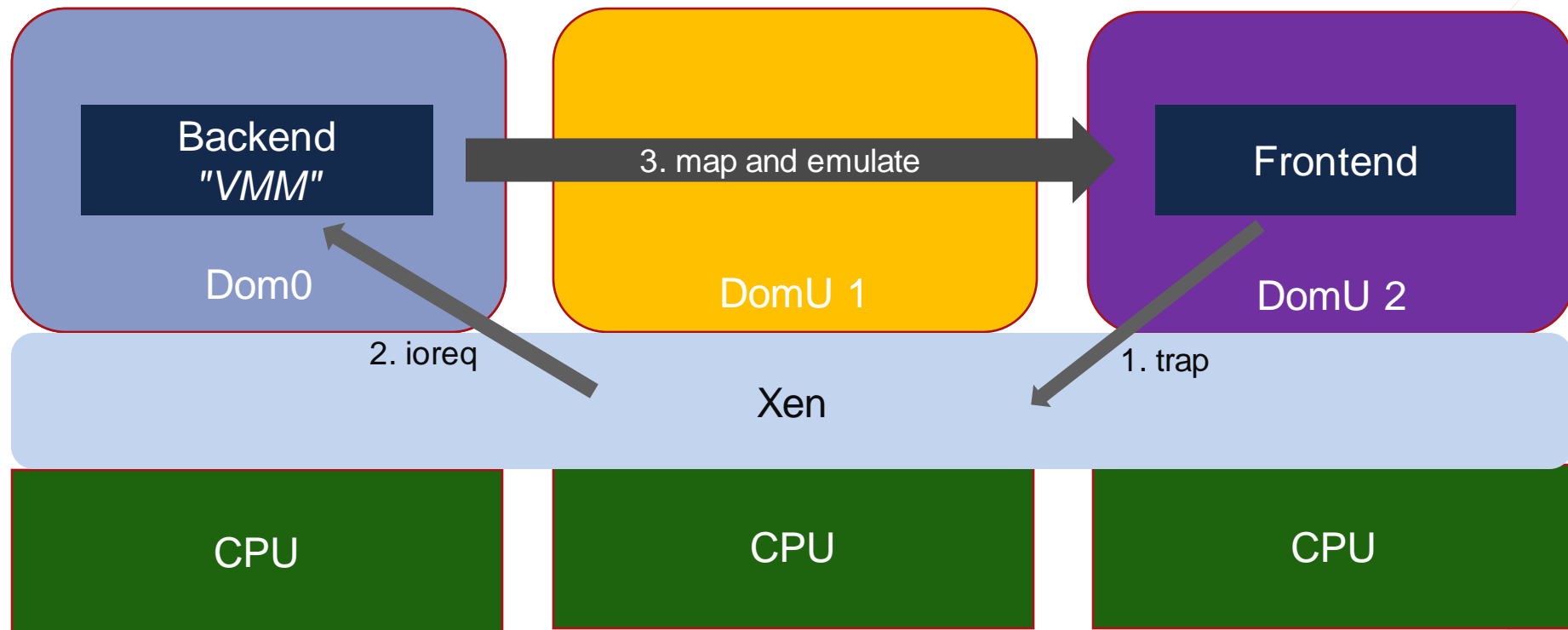
# Xen PV Drivers and Dom0less



- > **Domains booted in parallel**
- > **PV Drivers connections created after Dom0 is up and running**
- > **Advantages compared to regular non-Dom0less deployments:**
  - >> Domains are still started very quickly
  - >> Domains can immediately begin to perform critical tasks
  - >> Overall time to get PV Drivers up and running is shorter (no domain creation needed in Dom0)
- > **To become available by the end of the year (work by Hipert/Lab @ Unimore)**

- > **Frontend Drivers are available in most Operating Systems**
- > **"VMM" provides the backends (e.g. QEMU, kvmtools, etc.)**
- > **Pros:**
  - >> Many virtual device classes
- > **Cons:**
  - >> Backends are currently required to be privileged – backends must be in Dom0
    - Security implications
    - Safety implications
  - >> Support for Xen is available, but it requires non-upstream toolstack patches
  - >> No Dom0less support





## > IOREQ infrastructure upstream in Xen

- >> It enables VirtIO backends and any other emulators to run in Dom0 (e.g. QEMU)
- >> No support in the Xen tools for creating VirtIO frontends/backends yet (patch available)
- >> PoC with virtio-block by EPAM
- >> Requires Backends with full privileges, they have to be in Dom0
- >> Good performance with full privileges

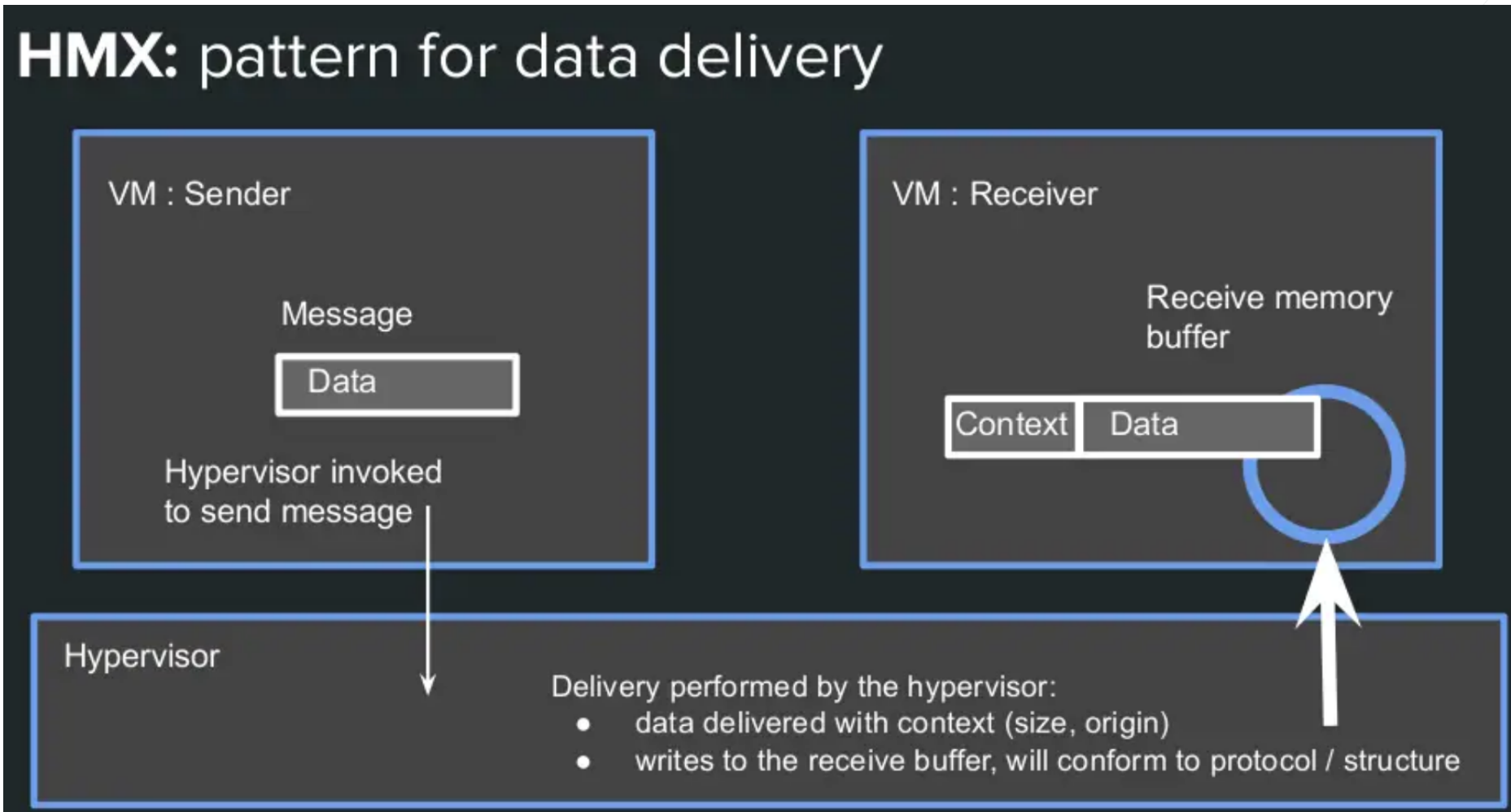
## > Support for Unprivileged Backend is work-in-progress by [Linaro Project Stratos](#)

- >> Based on memory copies to/from a pre-shared memory region
- >> Performance to be determined (never done before, underlying protocols designed for sharing)

## > How to enable VirtIO for Dom0less?

- >> Could VirtIO device hotplug be used to avoid synchronous waiting during boot?

## > Hypervisor-Mediated Data Transfers





## > Pros:

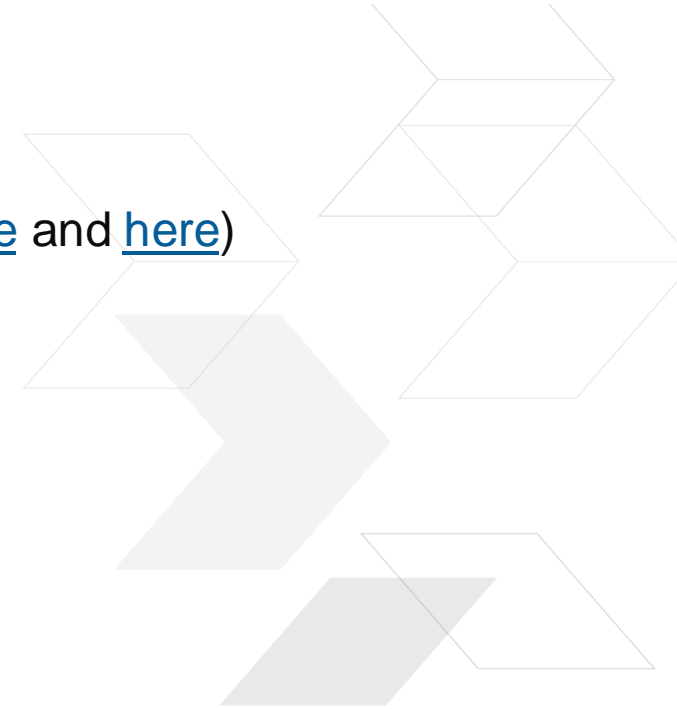
- >> Great performance and very strong security properties
  - Hypervisor checks against malicious data senders
  - Designed and optimized for memory copies
- >> More lightweight than Xen PV Drivers and VirtIO
  - No Xenstore, no PV backends, no VMM needed
  - Requires Event Channels and Argo drivers (BSD drivers available [here](#) and [here](#))
- >> Straightforward Dom0less enablement: no need for any kind of "wait"
  - No need to wait for Dom0 to complete booting to communicate with other VMs

## > Current Status:

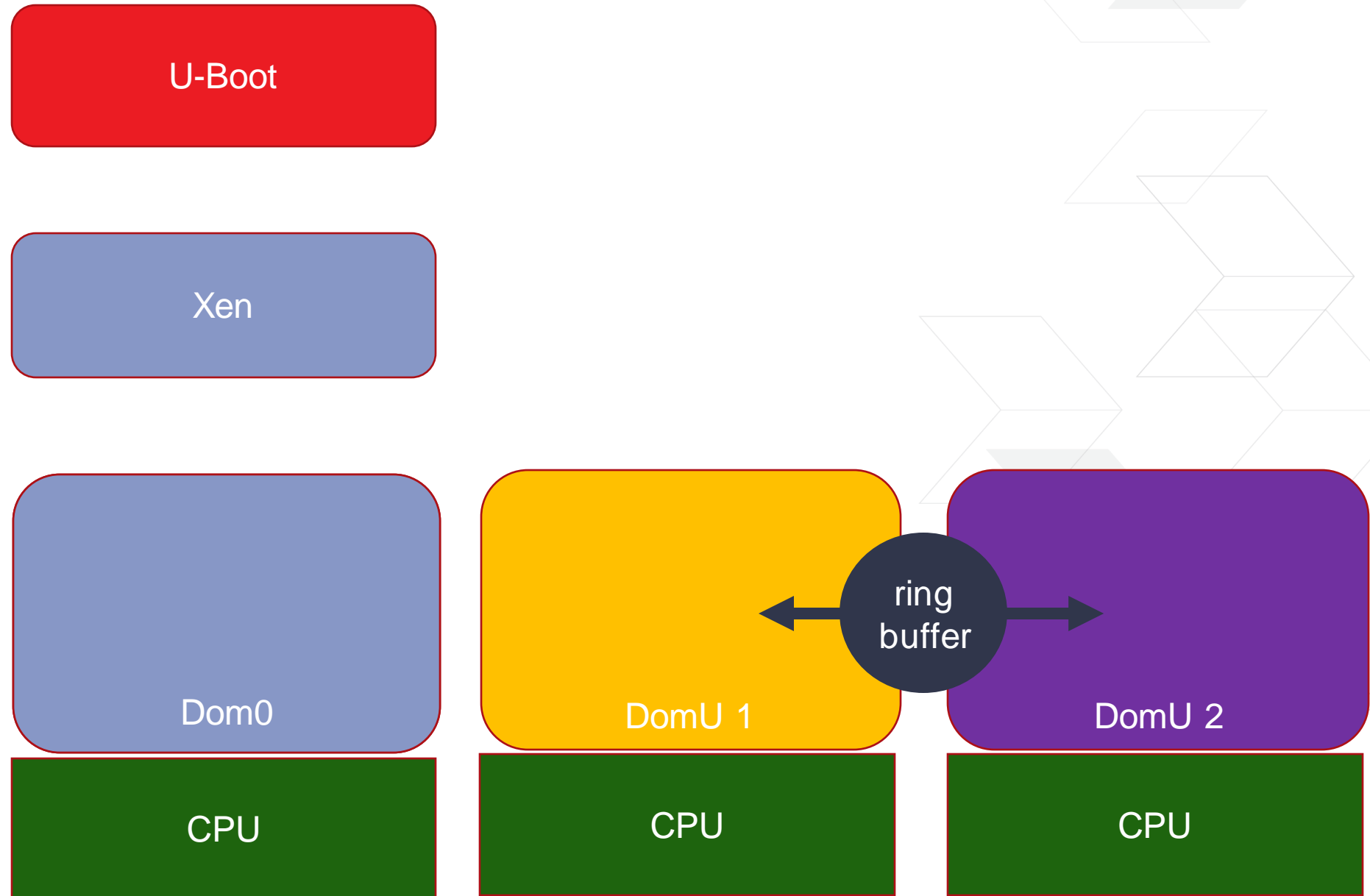
- >> It requires one Linux patch to work with Dom0less
  - Thanks Alec Kwapis from DornerWorks!

## > Cons:

- >> Requires Argo driver and Xen event channels for notifications



# Static Shared Memory and Interrupts



# Static Shared Memory and Interrupts



## > Plain shared memory region

- >> Configured at "build time"
- >> Guests setups ring buffers over shared memory
- >> Can use OpenAMP RPMesg or any other communication libraries based on shared memory

## > Interrupt-based notifications, work with any OSes

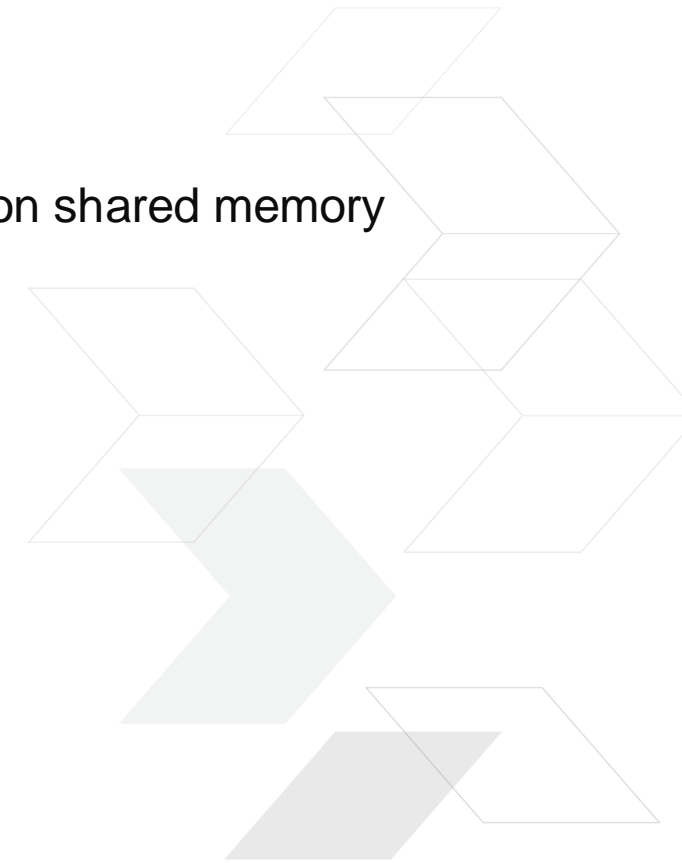
- >> [New hypercall to inject SGIs](#) (patch by Xilinx)

## > Pros:

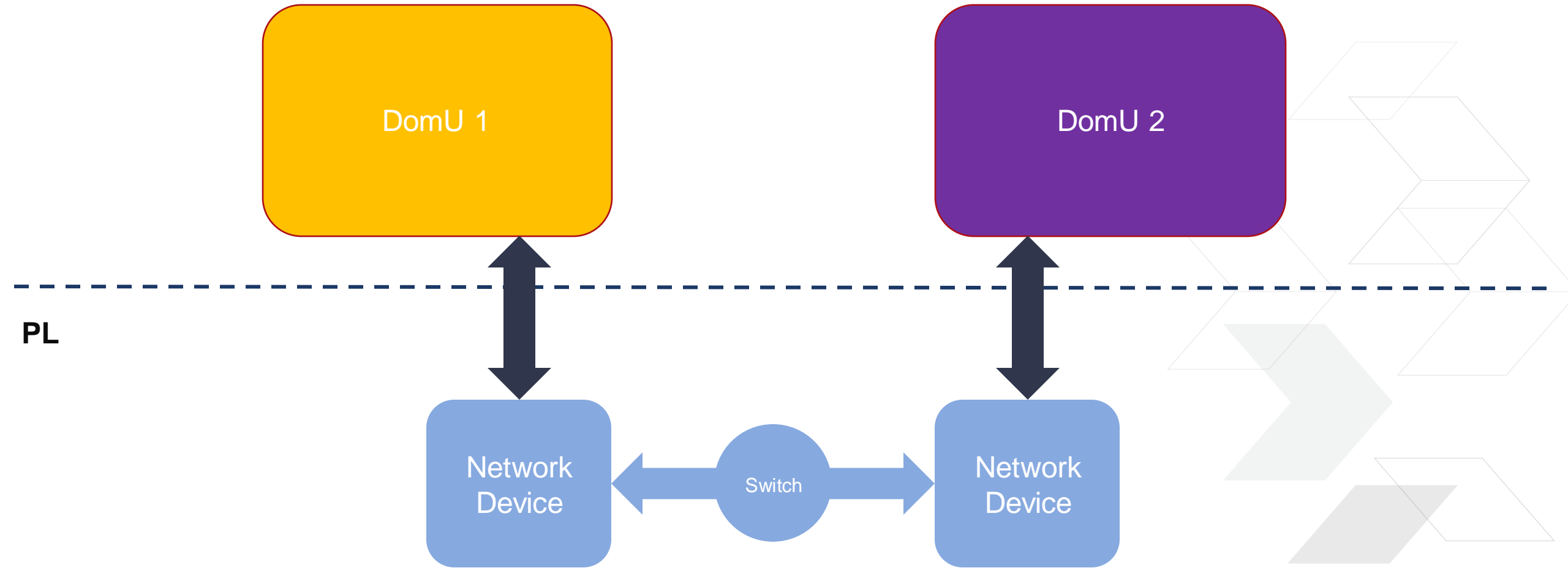
- >> Very simple
- >> Works with any OS
- >> Great performance if used correctly

## > Cons:

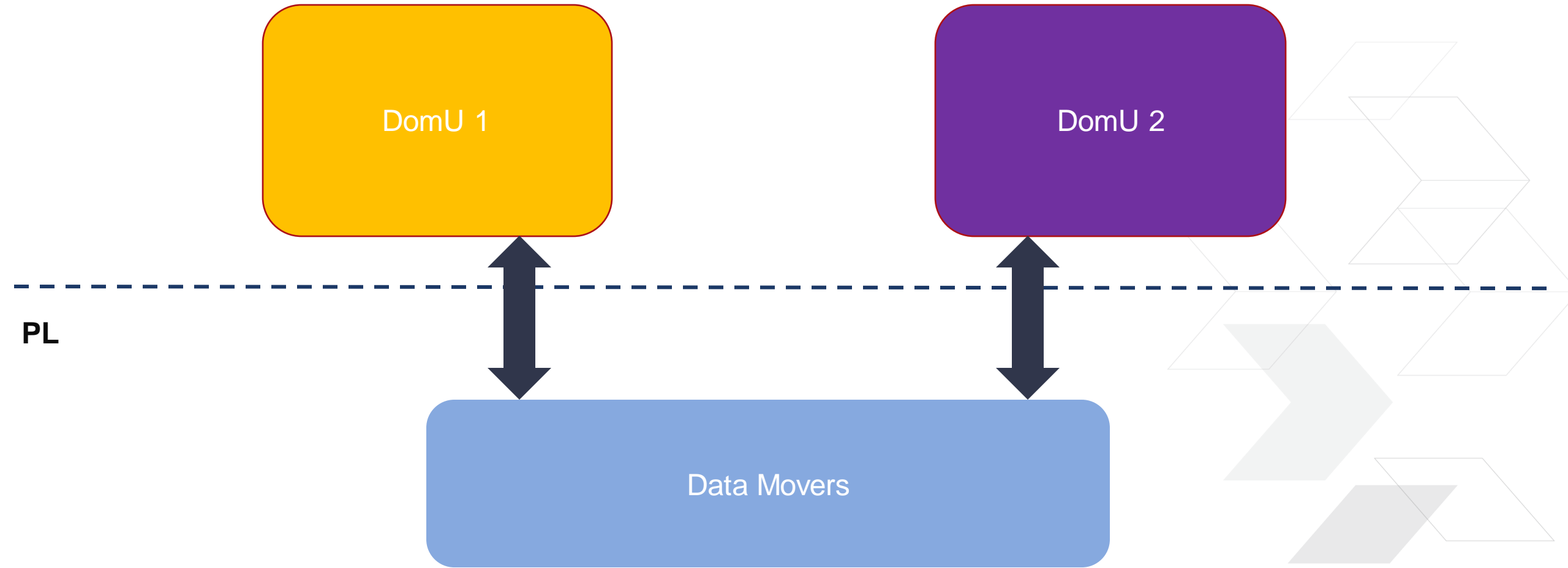
- >> One non-upstream patch to enable interrupt notifications
- >> Require your own communication library
- >> No dynamic connections



# PL-based communication mechanisms



# PL-based communication mechanisms



# PL-based communication mechanisms

- > **Create Data Movers in Programmable Logic**
  - >> From simple Network Devices to optimized Data Movers
- > **Assign PL resources to VMs**
- > **VMs use PL to send and receive data to/from other VMs**
- > **Pros:**
  - >> Fastest for larger data sizes
  - >> Userspace drivers only
  - >> Easy to enable in any OS
- > **Cons:**
  - >> Requires PL



# Summary

Solution	Upstream Status for regular Xen	Upstream Status for Dom0less	VM-to-VM Communication vs. Device Virtualization	Compatibility	Performance	Unprivileged Backends
Plain shared memory & interrupts	<a href="#">Patch available for interrupts</a>	<a href="#">Patch available for interrupts</a>	Static VM-to-VM Communication	Can run anywhere	High if implemented correctly	Yes
Argo	Upstream	<a href="#">One patch for Linux available</a>	Dynamic VM-to-VM Communication	Linux, Windows with a small effort	High	Yes
Xen PV Drivers	Upstream	Patches available soon	Unprivileged Device Virtualization	Most traditional OSes (Linux, Windows, BSDs)	High	Yes
VirtIO	Hypervisor: upstream	No	Privileged Device Virtualization	Most traditional OSes (Linux, Windows, BSDs)	High with full privileged	No (work in progress)
	Toolstack: <a href="#">patches available</a>				Otherwise: ?	

# Conclusions

- > **Several solutions are already available, but nothing works out of the box yet**
- > **No one-size fits all:**
  - >> Shared memory and notifications: best for OS compatibility
  - >> Argo: best for VM-to-VM communication
  - >> Xen PV Drivers: best for virtual devices with unprivileged backends
  - >> VirtIO: best for virtual device classes available



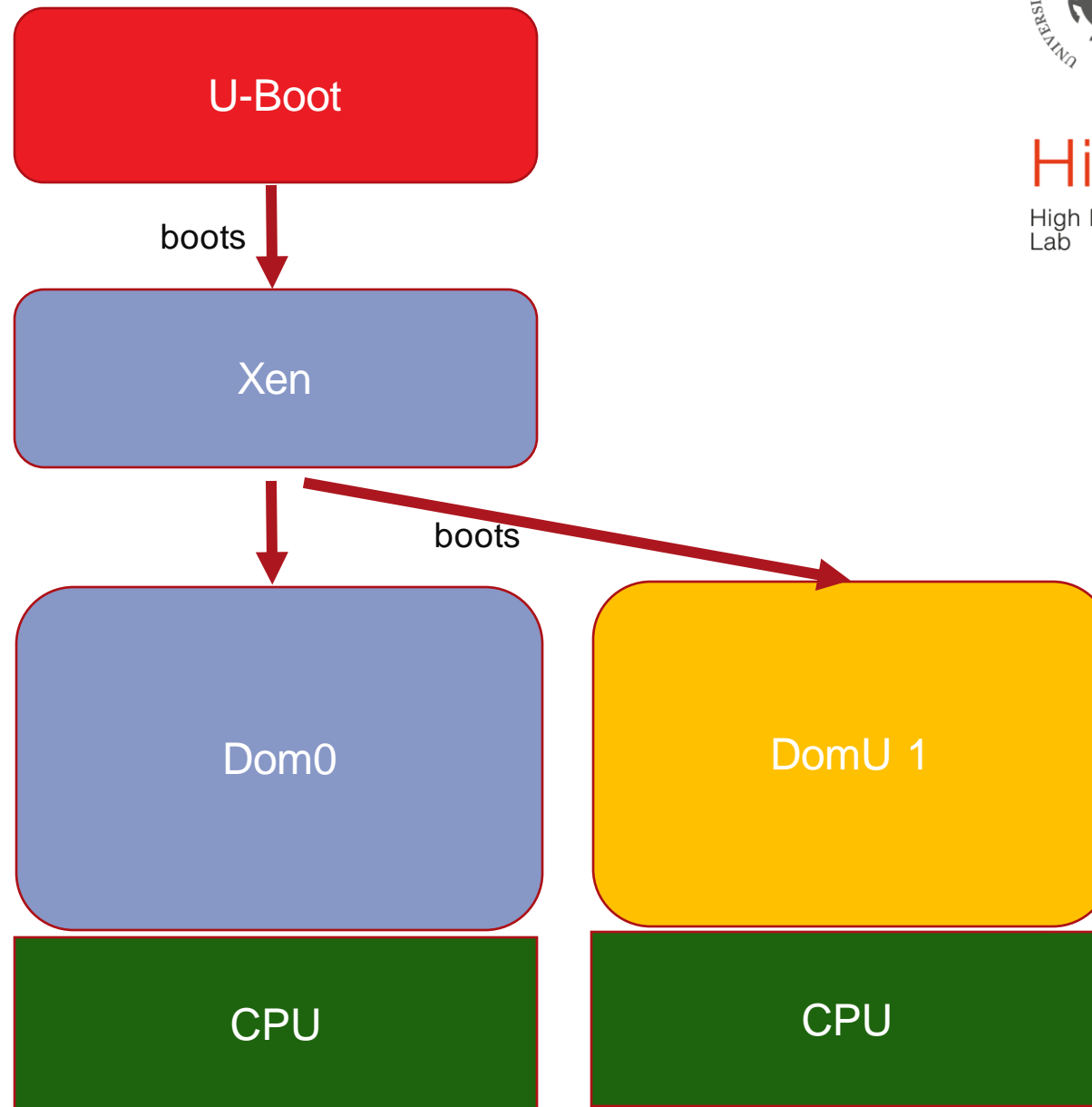


# Demo

By Luca Miccio and Marco Solieri



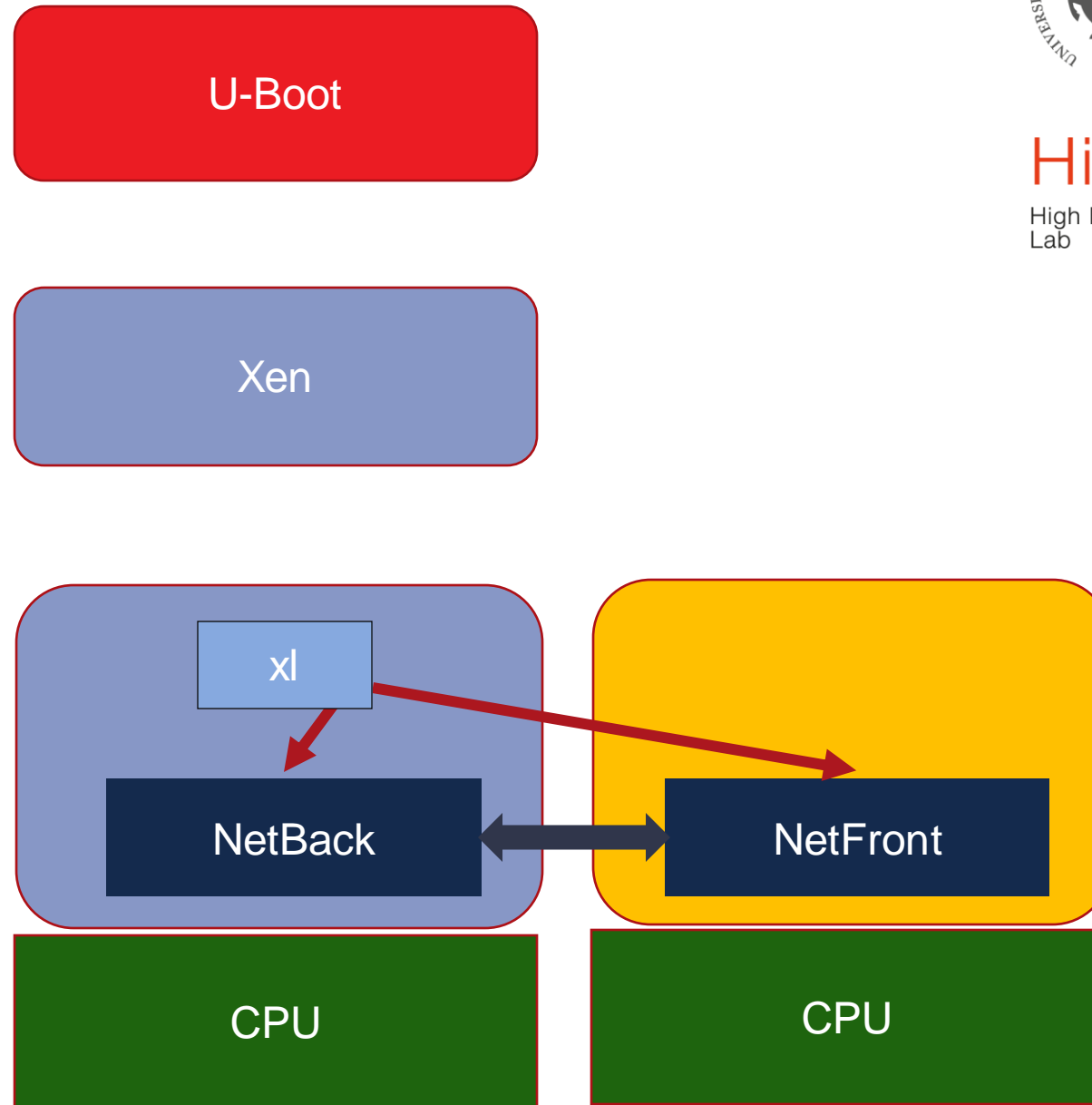
# Demo: Dom0less + PV Drivers



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